

# **FLI Software Development Library**

— Version 1.40 —

*Windows and Linux support for FLI CCD cameras, filter  
wheels, and focusers.*

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**Introduction**

This library provides a core set of functions for programming FLI CCD cameras, filter wheels, and focusers under Windows and Linux. The type definitions, function prototypes, and definitions/enumerations of constant values used by library functions are specified in `libfli.h`. All library functions return zero on successful completion, and non-zero if an error occurred. The exact nature of an error can be found by treating the negative of a function's return value as a system error code, for example:

```
if ((err = FLIOpen(&dev, name, domain))
    {
    fprintf(stderr, "Error FLIOpen: %s\n", strerror((int)-err));
    exit(1);
    }
```

## Library Defined Types

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2.1  
typedef long **fidev\_t**

*An opaque handle used by library functions to refer to FLI hardware*

An opaque handle used by library functions to refer to FLI hardware

## 2.2

```
typedef long flidomain_t
```

*The domain of an FLI device.*

The domain of an FLI device. This consists of a bitwise ORed combination of interface method and device type. Valid interfaces are `FLIDOMAIN_PARALLEL_PORT`, `FLIDOMAIN_USB`, `FLIDOMAIN_SERIAL`, and `FLIDOMAIN_INET`. Valid device types are `FLIDEVICE_CAMERA`, `FLIDOMAIN_FILTERWHEEL`, and `FLIDOMAIN_FOCUSER`.

**See Also:** `FLIOpen`  
`FLIList`

## 2.3

```
typedef long fliframe_t
```

*The frame type for an FLI CCD camera device.*

The frame type for an FLI CCD camera device. Valid frame types are `FLI_FRAME_TYPE_NORMAL` and `FLI_FRAME_TYPE_DARK`.

**See Also:** `FLISetFrameType`

## 2.4

```
typedef long flibitdepth_t
```

*The gray-scale bit depth for an FLI camera device.*

The gray-scale bit depth for an FLI camera device. Valid bit depths are `FLI_MODE_8BIT` and `FLI_MODE_16BIT`.

**See Also:** `FLISetBitDepth`

## 2.5

```
typedef long flishutter_t
```

*Type used for shutter operations for an FLI camera device.*

Type used for shutter operations for an FLI camera device. Valid shutter types are `FLI_SHUTTER_CLOSE`, `FLI_SHUTTER_OPEN`, `FLI_SHUTTER_EXTERNAL_TRIGGER`, `FLI_SHUTTER_EXTERNAL_TRIGGER_LOW`, and `FLI_SHUTTER_EXTERNAL_TRIGGER_HIGH`.

**See Also:** `FLIControlShutter`

## 2.6

```
typedef long flibgflush_t
```

*Type used for background flush operations for an FLI camera device.*

Type used for background flush operations for an FLI camera device. Valid bgflush types are `FLI_BGFLUSH_STOP` and `FLI_BGFLUSH_START`.

**See Also:** `FLIControlBackgroundFlush`

## 2.7

```
typedef long flichannel_t
```

*Type used to determine which temperature channel to read.*

Type used to determine which temperature channel to read. Valid channel types are `FLI_TEMPERATURE_INTERNAL` and `FLI_TEMPERATURE_EXTERNAL`.

**See Also:** `FLIReadTemperature`

## 2.8

```
typedef long flidebug_t
```

*Type specifying library debug levels.*

Type specifying library debug levels. Valid debug levels are `FLIDEBUG_NONE`, `FLIDEBUG_INFO`, `FLIDEBUG_WARN`, and `FLIDEBUG_FAIL`.

**See Also:** `FLISetDebugLevel`

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## 3.1

**LIBFLIAPI FLICancelExposure** (flidev\_t dev)

*Cancel an exposure for a given camera.*

Cancel an exposure for a given camera. This function cancels an exposure in progress by closing the shutter.

**Return Value:**           Zero           on success.  
                               Non-zero       on failure.

**Parameters:**           dev    Camera to cancel the exposure of.

**See Also:** FLIExposeFrame  
 FLIGetExposureStatus  
 FLISetExposureTime

## 3.2

**LIBFLIAPI FLIClose** (fidev\_t dev)

*Close a handle to a FLI device*

Close a handle to a FLI device

**Return Value:** Zero on success.  
 Non-zero on failure.

**Parameters:** dev The device handle to be closed.

**See Also:** FLIOpen

## 3.3

**LIBFLIAPI FLIGetArrayArea** (fidev\_t dev, long\* ul\_x, long\*  
 ul\_y, long\* lr\_x, long\* lr\_y)

*Get the array area of the given camera.*

Get the array area of the given camera. This function finds the *total* area of the CCD array for camera dev. This area is specified in terms of a upper-left point and a lower-right point. The upper-left x-coordinate is placed in ul\_x, the upper-left y-coordinate is placed in ul\_y, the lower-right x-coordinate is placed in lr\_x, and the lower-right y-coordinate is placed in lr\_y.

**Return Value:** Zero on success.  
 Non-zero on failure.

**Parameters:**

- `dev` Camera to get the array area of.
- `ul_x` Pointer to where the upper-left x-coordinate is to be placed.
- `ul_y` Pointer to where the upper-left y-coordinate is to be placed.
- `lr_x` Pointer to where the lower-right x-coordinate is to be placed.
- `lr_y` Pointer to where the lower-right y-coordinate is to be placed.

**See Also:** FLIGetVisibleArea  
FLISetImageArea

## 3.4

**LIBFLIAPI FLIFlushRow** (`flidev_t dev`, `long rows`, `long repeat`)

*Flush rows of a given camera.*

Flush rows of a given camera. This function flushes `rows` rows of camera `dev` `repeat` times.

**Return Value:**

- Zero on success.
- Non-zero on failure.

**Parameters:**

- `dev` Camera to flush rows of.
- `rows` Number of rows to flush.
- `repeat` Number of times to flush each row.

**See Also:** FLISetNFlashes

## 3.5

**LIBFLIAPI FLIGetFWRevision** (`flidev_t dev`, `long* fwrev`)

*Get firmware revision of a given device*

Get firmware revision of a given device

---

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Device to find the firmware revision of.  
fwrev Pointer to a long which will receive the  
firmwarerevision.

**See Also:** FLIGetModel  
FLIGetHWRevision  
FLIGetSerialNum

## 3.6

**LIBFLIAPI FLIGetHWRevision** (flidev\_t dev, long\* hwrev)

*Get the hardware revision of a given device*

Get the hardware revision of a given device

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Device to find the hardware revision of.  
hwrev Pointer to a long which will receive the  
hardwarerevision.

**See Also:** FLIGetModel  
FLIGetFWRevision  
FLIGetSerialNum

## 3.7

**LIBFLIAPI FLIGetLibVersion** (char\* ver, size\_t len)

*Get the current library version.*

Get the current library version. This function copies up to `len - 1` characters of the current library version string followed by a terminating `NULL` character into the buffer pointed to by `ver`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `ver` Pointer to a character buffer where the library versionstring is to be placed.  
`len` The size in bytes of the buffer pointed to by `ver`.

## 3.8

**LIBFLIAPI FLIGetModel** (`flidev_t dev`, `char* model`, `size_t len`)

*Get the model of a given device.*

Get the model of a given device. This function copies up to `len - 1` characters of the model string for device `dev`, followed by a terminating NULL character into the buffer pointed to by `model`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Device to find model of.  
`model` Pointer to a character buffer where the model string is to be placed.  
`len` The size in bytes of buffer pointed to by `model`.

**See Also:** FLIGetHWRevision  
FLIGetFWRevision  
FLIGetSerialNum

## 3.9

**LIBFLIAPI FLIGetPixelSize** (`flidev_t dev`, `double* pixel_x`, `double* pixel_y`)

*Find the dimensions of a pixel in the array of the given device*

Find the dimensions of a pixel in the array of the given device

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Device to find the pixel size of.  
pixel\_x Pointer to a double which will receive the size (inmicrons) of a pixel in the x direction.  
pixel\_y Pointer to a double which will receive the size (inmicrons) of a pixel in the y direction.

**See Also:** FLIGetArrayArea  
FLIGetVisibleArea

### 3.10

**LIBFLIAPI FLIGetVisibleArea** (flidev\_t dev, long\* ul\_x, long\* ul\_y, long\* lr\_x, long\* lr\_y)

*Get the visible area of the given camera.*

Get the visible area of the given camera. This function finds the *visible* area of the CCD array for the camera dev. This area is specified in terms of a upper-left point and a lower-right point. The upper-left x-coordinate is placed in ul\_x, the upper-left y-coordinate is placed in ul\_y, the lower-right x-coordinate is placed in lr\_x, the lower-right y-coordinate is placed in lr\_y.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Camera to get the visible area of.  
ul\_x Pointer to where the upper-left x-coordinate is to beplaced.  
ul\_y Pointer to where the upper-left y-coordinate is to beplaced.  
lr\_x Pointer to where the lower-right x-coordinate is to beplaced.  
lr\_y Pointer to where the lower-right y-coordinate is to beplaced.

**See Also:** FLIGetArrayArea  
FLISetImageArea

## 3.11

**LIBFLIAPI FLIOpen** (flidev\_t\* dev, char\* name, flidomain\_t domain)

*Get a handle to an FLI device.*

Get a handle to an FLI device. This function requires the filename and domain of the requested device. Valid device filenames can be obtained using the `FLIList()` function. An application may use any number of handles associated with the same physical device. When doing so, it is important to lock the appropriate device to ensure that multiple accesses to the same device do not occur during critical operations.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:**

dev	Pointer to where a device handle will be placed.
name	Pointer to a string where the device filename to be opened is stored. For parallel port devices that are not probed by <code>FLIList()</code> (Windows 95/98/Me), place the address of the parallel port in a string in ascii form ie: "0x378".
domain	Domain to apply to name for device opening. This is a bitwise ORed combination of interface method and devicetype. Valid interfaces include <code>FLIDOMAIN_PARALLEL_PORT</code> , <code>FLIDOMAIN_USB</code> , <code>FLIDOMAIN_SERIAL</code> , and <code>FLIDOMAIN_INET</code> . Valid device types include <code>FLIDEVICE_CAMERA</code> , <code>FLIDOMAIN_FILTERWHEEL</code> , and <code>FLIDOMAIN_FOCUSER</code> .

**See Also:** `FLIList`  
`FLIClose`  
`flidomain_t`

## 3.12

**LIBFLI API FLISetDebugLevel** (char\* host, flidebug\_t level)

*Enable debugging of API operations and communications.*

Enable debugging of API operations and communications. Use this function in combination with FLIDebug to assist in diagnosing problems that may be encountered during programming.

When using Microsoft Windows operating systems, creating an empty file C:\FLIDBG.TXT will override this option. All debug output will then be directed to this file.

<b>Return Value:</b>	Zero	on success.
	Non-zero	on failure.
<b>Parameters:</b>	host	Name of the file to send debugging information to. This parameter is ignored under Linux where <code>syslog(3)</code> is used to send debug messages (see <code>syslog.conf(5)</code> for how to configure <code>syslogd</code> ).
	level	Debug level. A value of <code>FLIDEBUG_NONE</code> disables debugging. Values of <code>FLIDEBUG_FAIL</code> , <code>FLIDEBUG_WARN</code> , and <code>FLIDEBUG_INFO</code> enable progressively more verbose debug messages.

## 3.13

**LIBFLI API FLISetExposureTime** (flidev\_t dev, long exptime)

*Set the exposure time for a camera.*

Set the exposure time for a camera. This function sets the exposure time for the camera `dev` to `exptime` msec.

---

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Camera to set the exposure time of.  
exptime Exposure time in msec.

**See Also:** FLIExposeFrame  
FLICancelExposure  
FLIGetExposureStatus

## 3.14

**LIBFLIAPI FLISetHBin** (flidev\_t dev, long hbin)

*Set the horizontal bin factor for a given camera.*

Set the horizontal bin factor for a given camera. This function sets the horizontal bin factor for the camera `dev` to `hbin`. The valid range of the `hbin` parameter is from 1 to 16.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Camera to set horizontal bin factor of.  
hbin Horizontal bin factor.

**See Also:** FLISetVBin  
FLISetImageArea

## 3.15

**LIBFLIAPI FLISetFrameType** (flidev\_t dev, fliframe\_t frametype)

*Set the frame type for a given camera.*

Set the frame type for a given camera. This function sets the frame type for camera `dev` to `frametype`. The `frametype` parameter is either `FLI_FRAME_TYPE_NORMAL` for

a normal frame where the shutter opens or `FLI_FRAME_TYPE_DARK` for a dark frame where the shutter remains closed.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `cam` Camera to set the frame type of.  
`frametype` Frame type: `FLI_FRAME_TYPE_NORMAL` or `FLI_FRAME_TYPE_DARK`.

**See Also:** `fliframe_t`  
`FLIExposeFrame`

## 3.16

**LIBFLIAPI FLISetImageArea** (`flidev_t dev`, `long ul_x`, `long ul_y`,  
`long lr_x`, `long lr_y`)

*Set the image area for a given camera.*

Set the image area for a given camera. This function sets the image area for camera `dev` to an area specified in terms of a upper-left point and a lower-right point. The upper-left x-coordinate is `ul_x`, the upper-left y-coordinate is `ul_y`, the lower-right x-coordinate is `lr_x`, and the lower-right y-coordinate is `lr_y`. Note that the given lower-right coordinate must take into account the horizontal and vertical bin factor settings, but the upper-left coordinate is absolute. In other words, the lower-right coordinate used to set the image area is a virtual point  $(lr'_x, lr'_y)$  determined by:

$$lr'_x = ul_x + (lr_x - ul_x) / hbin$$

$$lr'_y = ul_y + (lr_y - ul_y) / vbin$$

Where  $(lr'_x, lr'_y)$  is the coordinate to pass to the `FLISetImageArea` function,  $(ul_x, ul_y)$  and  $(lr_x, lr_y)$  are the absolute coordinates of the desired image area, `hbin` is the horizontal bin factor, and `vbin` is the vertical bin factor.

**Return Value:** Zero on success.  
Non-zero on failure.

---

**Parameters:**

<code>dev</code>	Camera to set image area of.
<code>ul_x</code>	Upper-left x-coordinate of image area.
<code>ul_y</code>	Upper-left y-coordinate of image area.
<code>lr_x</code>	Lower-right x-coordinate of image area ( $lr'_x$ from above).
<code>lr_y</code>	Lower-right y-coordinate of image area ( $lr'_y$ from above).

**See Also:** FLIGetVisibleArea  
FLIGetArrayArea

## 3.17

**LIBFLIAPI FLISetVBin** (flidev\_t dev, long vbin)

*Set the vertical bin factor for a given camera.*

Set the vertical bin factor for a given camera. This function sets the vertical bin factor for the camera `dev` to `vbin`. The valid range of the `vbin` parameter is from 1 to 16.

**Return Value:**

Zero	on success.
Non-zero	on failure.

**Parameters:**

<code>dev</code>	Camera to set vertical bin factor of.
<code>vbin</code>	Vertical bin factor.

**See Also:** FLISetHBin  
FLISetImageArea

## 3.18

**LIBFLIAPI FLIGetExposureStatus** (flidev\_t dev, long\* timeleft)

*Find the remaining exposure time of a given camera.*

Find the remaining exposure time of a given camera. This function places the remaining exposure time (in milliseconds) in the location pointed to by `timeleft`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera to find the remaining exposure time of.  
`timeleft` Pointer to where the remaining exposure time (in milliseconds) will be placed.

**See Also:** `FLIExposeFrame`  
`FLICancelExposure`  
`FLISetExposureTime`

## 3.19

**LIBFLIAPI FLISetTemperature** (`flidev_t dev`, `double temperature`)

*Set the temperature of a given camera.*

Set the temperature of a given camera. This function sets the temperature of the CCD camera `dev` to `temperature` degrees Celsius. The valid range of the `temperature` parameter is from -55 C to 45 C.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera device to set the temperature of.  
`temperature` Temperature in Celsius to set CCD camera cold finger to.

**See Also:** `FLIGetTemperature`

## 3.20

**LIBFLIAPI FLIGetTemperature** (`flidev_t dev`, `double* temperature`)

*Get the temperature of a given camera.*

Get the temperature of a given camera. This function places the temperature of the CCD camera cold finger of device `dev` in the location pointed to by `temperature`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera device to get the temperature of.  
`temperature` Pointer to where the temperature will be placed.

**See Also:** `FLISetTemperature`

## 3.21

**LIBFLIAPI FLIGrabRow** (`flidev_t dev, void* buff, size_t width`)

*Grab a row of an image.*

Grab a row of an image. This function grabs the next available row of the image from camera device `dev`. The row of width `width` is placed in the buffer pointed to by `buff`. The size of the buffer pointed to by `buff` must take into account the bit depth of the image, meaning the buffer size must be at least `width` bytes for an 8-bit image, and at least `2*width` for a 16-bit image.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera whose image to grab the next available row from.  
`buff` Pointer to where the next available row will be placed.  
`width` Row width in pixels.

**See Also:** `FLIGrabFrame`

## 3.22

**LIBFLIAPI FLIExposeFrame** (`flidev_t dev`)

*Expose a frame for a given camera.*

Expose a frame for a given camera. This function exposes a frame according to the settings (image area, exposure time, bit depth, etc.) of camera `dev`. The settings of `dev` must be valid for the camera device. They are set by calling the appropriate set library functions. This function returns after the exposure has started.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera to expose the frame of.

**See Also:** FLISetExposureTime  
FLISetFrameType  
FLISetImageArea  
FLISetHBin  
FLISetVBin  
FLISetNFlashes  
FLISetBitDepth  
FLIGrabFrame  
FLICancelExposure  
FLIGetExposureStatus

## 3.23

**LIBFLIAPI FLISetBitDepth** (`flidev_t dev`, `flibitdepth_t bitdepth`)

*Set the gray-scale bit depth for a given camera.*

Set the gray-scale bit depth for a given camera. This function sets the gray-scale bit depth of camera `dev` to `bitdepth`. The `bitdepth` parameter is either `FLI_MODE_8BIT` for 8-bit mode or `FLI_MODE_16BIT` for 16-bit mode. Many cameras do not support this mode.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera to set the bit depth of.  
`bitdepth` Gray-scale bit depth: `FLI_MODE_8BIT`  
or `FLI_MODE_16BIT`.

**See Also:** `flibitdepth_t`  
`FLIExposeFrame`

## 3.24

**LIBFLIAPI FLISetNFlushes** (flidev\_t dev, long nflushes)

*Set the number of flushes for a given camera.*

Set the number of flushes for a given camera. This function sets the number of times the CCD array of camera `dev` is flushed by the `FLIExposeFrame` *before* exposing a frame to `nflushes`. The valid range of the `nflushes` parameter is from 0 to 16. Some FLI cameras support background flushing. Background flushing continuously flushes the CCD eliminating the need for pre-exposure flushing.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera to set the number of flushes of.  
`nflushes` Number of times to flush CCD array before an exposure.

**See Also:** `FLIFlushRow`  
`FLIExposeFrame`  
`FLIControlBackgroundFlush`

## 3.25

**LIBFLIAPI FLIReadIOPort** (flidev\_t dev, long\* ioportset)

*Read the I/O port of a given camera.*

Read the I/O port of a given camera. This function reads the I/O port on camera `dev` and places the value in the location pointed to by `ioportset`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Camera to read the I/O port of.  
`ioportset` Pointer to where the I/O port data will be stored.

**See Also:** `FLIWriteIOPort`  
`FLIConfigureIOPort`

## 3.26

**LIBFLIAPI FLIWriteIOPort** (flidev\_t dev, long ioportset)*Write to the I/O port of a given camera.*

Write to the I/O port of a given camera. This function writes the value `ioportset` to the I/O port on camera `dev`.

**Return Value:** Zero on success.  
 Non-zero on failure.

**Parameters:** `dev` Camera to write I/O port of.  
`ioportset` Data to be written to the I/O port.

**See Also:** FLIReadIOPort  
 FLIConfigureIOPort

## 3.27

**LIBFLIAPI FLIConfigureIOPort** (flidev\_t dev, long ioportset)*Configure the I/O port of a given camera.*

Configure the I/O port of a given camera. This function configures the I/O port on camera `dev` with the value `ioportset`.

The I/O configuration of each pin on a given camera is determined by the value of `ioportset`. Setting a respective I/O bit enables the port bit for output while clearing an I/O bit enables to port bit for input. By default, all I/O ports are configured as inputs.

**Return Value:** Zero on success.  
 Non-zero on failure.

**Parameters:** `dev` Camera to configure the I/O port of.  
`ioportset` Data to configure the I/O port with.

**See Also:** FLIReadIOPort  
 FLIWriteIOPort

## 3.28

**LIBFLIAPI FLILockDevice** (fidev\_t dev)

*Lock a specified device.*

Lock a specified device. This function establishes an exclusive lock (mutex) on the given device to prevent access to the device by any other function or process.

**Return Value:**           Zero           on success.  
                          Non-zero    on failure.  
**Parameters:**           dev   Device to lock.  
**See Also:**               FLIUnlockDevice

## 3.29

**LIBFLIAPI FLIUnlockDevice** (fidev\_t dev)

*Unlock a specified device.*

Unlock a specified device. This function releases a previously established exclusive lock (mutex) on the given device to allow access to the device by any other function or process.

**Return Value:**           Zero           on success.  
                          Non-zero    on failure.  
**Parameters:**           dev   Device to unlock.  
**See Also:**               FLILockDevice

## 3.30

**LIBFLIAPI FLIControlShutter** (fidev\_t dev, flishutter\_t shutter)

*Control the shutter on a given camera.*

Control the shutter on a given camera. This function controls the shutter function on camera `dev` according to the `shutter` parameter.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Device to control the shutter of.  
`shutter` How to control the shutter. A value of `FLI_SHUTTER_CLOSE` closes the shutter and `FLI_SHUTTER_OPEN` opens the shutter. `FLI_SHUTTER_EXTERNAL_TRIGGER_LOW`, `FLI_SHUTTER_EXTERNAL_TRIGGER` causes the exposure to begin only when a logic LOW is detected on I/O port bit 0. `FLI_SHUTTER_EXTERNAL_TRIGGER_HIGH` causes the exposure to begin only when a logic HIGH is detected on I/O port bit 0. This setting may not be available on all cameras.

**See Also:** `flishutter.t`

### 3.31

**LIBFLI API FLIControlBackgroundFlush** (`flidev.t dev,`  
`flibgflush.t bgflush`)

*Enables background flushing of CCD array.*

Enables background flushing of CCD array. This function enables the background flushing of the CCD array camera `dev` according to the `bgflush` parameter. Note that this function may not succeed on all FLI products as this feature may not be available.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:**

dev	Device to control the background flushing of.
bgflush	Enables or disables background flushing. A value of <code>FLI_BGFLUSH_START</code> begins background flushing. It is important to note that background flushing is stopped whenever <code>FLIExposeFrame()</code> or <code>FLIControlShutter()</code> are called. <code>FLI_BGFLUSH_STOP</code> stops all background flush activity.

**See Also:** `flibgflush.t`

## 3.32

**LIBFLIAPI FLIList** (flidomain\_t domain, char\*\*\* names)

*List available devices.*

List available devices. This function returns a pointer to a NULL terminated list of device names. The pointer should be freed later with `FLIFreeList()`. Each device name in the returned list includes the filename needed by `FLIOpen()`, a separating semicolon, followed by the model name or user assigned device name.

**Return Value:**

Zero	on success.
Non-zero	on failure.

**Parameters:**

domain	Domain to list the devices of. This is a bitwise ORed combination of interface method and device type. Valid interfaces include <code>FLIDOMAIN_PARALLEL_PORT</code> , <code>FLIDOMAIN_USB</code> , <code>FLIDOMAIN_SERIAL</code> , and <code>FLIDOMAIN_INET</code> . Valid device types include <code>FLIDEVICE_CAMERA</code> , <code>FLIDOMAIN_FILTERWHEEL</code> , and <code>FLIDOMAIN_FOCUSER</code> .
names	Pointer to where the device name list will be placed.

**See Also:** `flidomain.t`, `FLIFreeList`, `FLIOpen`

## 3.33

**LIBFLIAPI FLIFreeList** (char\*\* names)

*Free a previously generated device list.*

Free a previously generated device list. Use this function after `FLIList()` to free the list of device names.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** names Pointer to the list.

**See Also:** FLIList

## 3.34

**LIBFLIAPI FLISetFilterPos** (fidev\_t dev, long filter)

*Set the filter wheel position of a given device.*

Set the filter wheel position of a given device. Use this function to set the filter wheel position of `dev` to `filter`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Filter wheel device handle.  
filter Desired filter wheel position.

**See Also:** FLIGetFilterPos

## 3.35

**LIBFLIAPI FLIGetFilterPos** (fidev\_t dev, long\* filter)

*Get the filter wheel position of a given device.*

Get the filter wheel position of a given device. Use this function to get the filter wheel position of `dev`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Filter wheel device handle.  
`filter` Pointer to where the filter wheel position will be placed.

**See Also:** `FLISetFilterPos`

---

**3.36**

**LIBFLIAPI FLIGetStepsRemaining** (`flidev_t dev`, `long* steps`)

*Get the number of motor steps remaining.*

Get the number of motor steps remaining. Use this function to determine if the stepper motor of `dev` is still moving.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Filter wheel device handle.  
`filter` Pointer to where the number of remaining steps will be placed.

**See Also:** `FLISetFilterPos`

---

**3.37**

**LIBFLIAPI FLIGetFilterCount** (`flidev_t dev`, `long* filter`)

*Get the filter wheel filter count of a given device.*

Get the filter wheel filter count of a given device. Use this function to get the filter count of filter wheel `dev`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Filter wheel device handle.  
`filter` Pointer to where the filter wheel filter count will be placed.

## 3.38

**LIBFLIAPI FLIStepMotorAsync** (`flidev_t dev`, long steps)

*Step the filter wheel or focuser motor of a given device.*

Step the filter wheel or focuser motor of a given device. Use this function to move the focuser or filter wheel `dev` by an amount `steps`. This function is non-blocking.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** `dev` Filter wheel or focuser device handle.  
`steps` Number of steps to move the focuser or filter wheel.

**See Also:** FLIGetStepperPosition

## 3.39

**LIBFLIAPI FLIStepMotor** (`flidev_t dev`, long steps)

*Step the filter wheel or focuser motor of a given device.*

Step the filter wheel or focuser motor of a given device. Use this function to move the focuser or filter wheel `dev` by an amount `steps`.

---

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Filter wheel or focuser device handle.  
steps Number of steps to move the focuser or filter wheel.

**See Also:** FLIGetStepperPosition

## 3.40

**LIBFLIAPI FLIGetStepperPosition** (flidev\_t dev, long\* position)

*Get the stepper motor position of a given device.*

Get the stepper motor position of a given device. Use this function to read the stepper motor position of filter wheel or focuser dev.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Filter wheel or focuser device handle.  
position Pointer to where the position of the stepper motor will be placed.

**See Also:** FLIStepMotor

## 3.41

**LIBFLIAPI FLIHomeFocuser** (flidev\_t dev)

*Home focuser dev.*

Home focuser dev. The home position is closed as far as mechanically possible.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Focuser device handle.

## 3.42

**LIBFLIAPI FLIGetFocuserExtent** (flidev\_t dev, long\* extent)

*Retrieve the maximum extent for FLI focuser dev*

Retrieve the maximum extent for FLI focuser dev

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Focuser device handle.  
extent Pointer to where the maximum extent of the focuser will be placed.

## 3.43

**LIBFLIAPI FLIReadTemperature** (flidev\_t dev, fchannel\_t channel, double\* temperature)

*Retrieve temperature from the FLI focuser dev.*

Retrieve temperature from the FLI focuser dev. Valid channels are `FLI_TEMPERATURE_INTERNAL` and `FLI_TEMPERATURE_EXTERNAL`.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** dev Focuser device handle.  
channel Channel to be read.  
extent Pointer to where the channel temperature will be placed.



3.46

```
LIBFLIAPI FLIListFirst (flidomain_t* domain, char* filename,
                        size_t fnlen, char* name, size_t namelen)
```

*Obtains the first device in the list.*

Obtains the first device in the list. Use this function to get the first domain, filename and name from the list of attached FLI devices created using the function FLICreateList(). Use FLIListNext() to obtain more found devices.

**Return Value:** Zero on success.  
Non-zero on failure.

**Parameters:** domain Pointer to where to domain of the device will be placed.  
filename Pointer to where the filename of the device will be placed.  
fnlen Length of the supplied buffer to hold the filename.  
name Pointer to where the name of the device will be placed.  
namelen Length of the supplied buffer to hold the name.

**See Also:** FLICreateList  
FLIDeleteList  
FLIListNext

3.47

```
LIBFLIAPI FLIListNext (flidomain_t* domain, char* filename,
                       size_t fnlen, char* name, size_t namelen)
```

*Obtains the next device in the list.*

